Kurzweil 1000 Series Developer Information

Kurzweil Music Systems, Inc.

Contents of this package:

- 1. Kurzweil 1000 Series MIDI Implementation
- 2. Kurzweil 1000 Series MIDI System Exclusive Messages
- 3. Kurzweil 1000 Series Binary Data Transfer Protocol How to talk to the K1000 over MIDI.
- 4. Kurzweil 1000 Series Object Overview Describes the basic structure of K1000 binary objects. Illustrated!

Kurzweil 1000 Series MIDI Implementation

Kurzweil Music Systems, Inc.

1st Edition: March '88

MIDI Modes

The 1000 series currently supports three modes of MIDI reception: Omni On/Poly, Omni Off/Poly and Multi. In Omni On mode, the channel number is ignored. In Omni Off (aka Poly) mode, only messages received on the basic channel are recognized. In Multi mode, all enabled MIDI channels are recognized.

Note On's and Off's

NOTE: The 1000 series products (in fact, all Kurzweil products) refer to <u>Middle C (MIDI key number 60) as C4</u>, in contrast to numerous software products which mistakenly call it C3. This is, as far as we know, an <u>international</u> <u>standard</u> to which we've been adhering since before we ever heard of MIDI. Included with this document is an appendix which lists the key numbers and their proper names.

The 1000 series responds to the entire range of MIDI key numbers although the actual, playable range depends on the selected program. (E.g., some of the sampled instruments have natural ranges which do not cover the entire keyboard.) It is also possible to restrict the MIDI key range on an individual MIDI channel via the master parameters. In general most programs respond over the range C0 (=12) thru C8 (=108).

The 1000 series also allows multi-layered programs, in which a single MIDI Note On may start multiple voices in the instrument. This technique is provided to allow creation of complex timbres from combinations of raw sounds; there is no efficiency gain by using layers. I.e., it takes the instrument just as long to start four layers from a single MIDI note on as it does to start four individual notes.

The lowest octave of key numbers, C-1 (=0) thru B-1 (=11), is available to control the intonation table reference key. When used with a suitable MIDI controller, this allows chromatic modulation in real-time while using a non-equally tempered intonation.

In the K1000 keyboard instrument, Note Off's are transmitted using the MIDI Note Off message \$8x kkk vvv. This can cause problems with certain simple minded MIDI processors (such as the Yamaha MEP4) which transpose the MIDI stream by only altering key numbers in Note On messages (\$9x) on the assumption that the MIDI controller is sending Note Off's as zero velocity Note On's. Currently, there is no solution to this problem but future versions of the software will add a master parameter to select the type of Note Off (real Note Off or zero velocity Note On) which is transmitted.

There is a layer-level parameter which allows the Note Off message to be ignored. This is provided so that programs can be created which play through their envelopes completely, until each note decays to silence. If the envelope doesn't decay, the note will sustain indefinitely.

In 1000 series software, both attack and release velocity are available (in normal and inverse form) as internal control sources; programs can be created which respond to these parameters. When a note is started, its release velocity is set to zero (and inverse release velocity is set to one). When the Note Off is received, the actual release velocity becomes available. Zero velocity Note On's which are received are treated as Note Off's with a velocity of 64.

Program Changes

The 1000 series responds to the full range of MIDI program change numbers. The numbers are mapped through an editable list (selected by the master parameter RxPMap) which selects the real, internal program number. Program

changes which reference non-existent programs are ignored. In general, it takes the instrument about as much time to change a program as it does to start a single layer note.

Control Changes

All MIDI control numbers are mapped thru a master table which may be replaced by a RAM copy.

Internally, the 1000 series represents all control values as signed, 15 bit fractions with a range of ± 1 . MIDI controls (except for the pitch wheel) are treated as uni-polar values with a range of 0 to 1. When a control source is used as a switch, it is considered to by ON if its value is greater than or equal to 0.5. This translates into an MSB value of 64 or greater. The details of how MIDI control values are mapped to internal control values are as follows:

The continuous control MSB's (control numbers 1 thru 31) and LSB's (control numbers 33 thru 63) are recorded for all sixteen MIDI channels. When an MSB message is received, the corresponding LSB is forced to zero if the MSB value is zero; otherwise the LSB is set to all ones. Thus, a control value of 0 yields an internal value of 0, while a control value of 127 (\$7F) yields an internal value of -1 (\$7FFF). Thus, it is desirable to transmit the MSB of any continuous controller first, followed by the LSB.

The continuous 'switches' (control numbers 64 thru 95) are treated similarly to the continuous control MSBs. When an MSB of zero is received, the LSB of the internal value is set to zero, otherwise it is set to all one's. Thus the internal value of any control is

value = 256 * MSB + 2 * LSB

In general, the 1000 series software makes no distinction between internal control sources (e.g., envelopes or LFO's) and external control sources (i.e., MIDI controls). This allows any MIDI control source to be patched to any control input.

Certain well-defined control numbers are given special treatment:

7 Volume MSB

39 Volume LSB

The volume control may be thought of as controlling an imaginary output VCA. Thus it is completely independent of the note amplitude. This can cause problems with certain wind controllers which transmit MIDI volume as a way of creating a real-time envelope. Switches are provided to ignore MIDI volume at both the layer and the MIDI channel. In addition, the mapping the control values to loudness is controlled by a master table which may be overridden by a RAM copy.

64 Sustain Pedal.

When this switch is on, playing notes are held until the switch is off or until they have decayed to silence. A layer-level parameter is provided to ignore the sustain pedal.

66 Sostenuto Pedal

This switch behaves like the sustain pedal, but only notes whose keys were down when the pedal was depressed are held. A layer-level parameter is provided to ignore the sostenuto pedal.

67 Soft Pedal

At note start, the value of this control (0 to 1) is multiplied by the layer-level soft pedal range parameter $(\pm dB)$ and the result is subtracted from the initial amplitude of the note. The sign of the range parameter determines whether the notes get louder or softer. When this control is used with a switch pedal, its value will be either 0 or 1, but since it responds to the full range of MIDI control values, it can actually be used as a continuous attenuator. Once a note has been started, this control has no effect.

69 Suspend Pedal (aka Freeze Pedal)

This switch behaves like the sostenuto pedal, but in addition to sustaining the note, the envelopes are frozen as well. A layer-level parameter is provided to ignore the suspend pedal.

121 All Controls Off

When this message is received, all controls are reset to zero, with the following exceptions: volume (#7 and #39) is set to maximum (\$7FFF), balance (#8 and #40) and pan (#10 and #42) are set to center point (\$4000).

122 Local Control On/Off

This message is only recognized by the K1000 on the basic MIDI channel (it is ignored in rack-mount equipment).

123 All Notes Off

The All Notes Off message is recognized in all MIDI modes. In particular, it is not ignored in Omni On mode. This is contrary to the MIDI spec but represents the unanimous opinion of our users.

NOTE: most Roland equipment (e.g., MKB-1000, D-50, etc.) sends an All Notes Off message when all the keys are released. In order to deal with this, the 1000 series includes a master parameter which allows you to ignore the all notes off message. We call it the "Roland Switch." And I just discovered (as I am working on this document) that Kawai equipment exhibits the same behavior.

124 Omni Off

125 Omni On

When not in Multi Mode, the Omni On/Off messages are recognized on the basic MIDI channel only. In Multi Mode, these messages are ignored. This is contrary to the MIDI spec but represents the unanimous opinion of our users.

When the instrument is in edit mode, the following control numbers are also recognized:

- 6 Data Entry Slider MSB
- 38 Data Entry Slider LSB
- 96 Data Increment
- 97 Data Decrement

The data entry slider (control numbers 6 and 38) and the data increment/decrement buttons (control numbers 96 and 97) are recognized when the instrument is in edit mode.

98 Non-Registered Parameter Select LSB

99 Non-Registered Parameter Select MSB

When the instrument is in edit mode, the non-registered parameter select MSB selects the edit menu and the LSB selects the parameter within the menu. However, because the menu selection varies based on high or low level editing mode and in some cases (e.g., envelopes) the actual parameter list varies, there is no absolute mapping between select values and actual parameters.

Pitch Wheel

Currently, the pitch wheel is the only MIDI control which has an internal range which is bipolar (i.e., ± 1). The actual conversion from MIDI data values to internal form is

pitch wheel value = 256 * MSB + 2 * LSB - \$4000

Future implementations of the software will provide an absolute value pitch wheel control source with a range of 0 to 1 in both directions, to allow effects to be tied to pitch bending in either direction.

Mono and Poly Pressure

Both Mono Pressure and Poly Pressure messages are recognized. Internally they are treated as additional control sources but their internal values are derived by a mapping table rather than a direct conversion. Note that both pressure sources are treated as separate entities. Thus it is possible to create programs which have separate responses to

both Mono and Poly Pressure, provided you have a MIDI controller which transmits both. On the other hand, a program which responds to Poly Pressure will not respond to Mono Pressure, and vice versa. Future versions of the software will provide some master parameter to allow global selection of the pressure source.

Poly Pressure messages are only recognized for keys which have notes playing. Note that Poly Pressure messages transmitted after a Note Off message has been received may still be acted upon if the note is still playing (e.g., as a result of a slow decay). This can actually occur if you strike the same key twice. If the envelope has a long decay, the pressure messages for the new note will also affect the previous note.

System Common/Real-Time

All system common (except for System Elusives [SIC]) and real-time messages are ignored.

Note Names and Key Numbers

Octave	С	C#	D	D#	Е	F	F#	G	G#	А	A#	В
-1	0	1	2	3	4	5	6	7	8	9	10	11
0	12	13	14	15	16	17	18	19	20	21	22	23
1	24	25	26	27	28	29	30	31	32	33	34	35
2	36	37	38	39	40	41	42	43	44	45	46	47
3	48	49	50	51	52	53	54	55	56	57	58	59
4	60	61	62	63	64	65	66	67	68	69	70	71
5	72	73	74	75	76	77	78	79	80	81	82	83
6	84	85	86	87	88	89	90	91	92	93	94	95
7	96	97	98	99	100	101	102	103	104	105	106	107
8	108	109	110	111	112	113	114	115	116	117	119	
9	120	121	122	123	124	125	126	127				

Kurzweil 1000 Series System Exclusive Messages

Kurzweil Music Systems, Inc.

2nd Edition: April '88 1st Edition: February '88

The 2nd edition of this document provides a correction to the front panel button code list.

These notes describe the current state of system exclusive messages in the K1000 series. All values are expressed in hexadecimal.

Version Request

The K1000 responds to the standard MIDI version request message:

The 1000 defaults to a device ID of \$00, although it may be set to any value from \$00 to \$7F

\$F0	\$7E <device id=""> \$06 \$02 \$07</device>	; response ; Kurzweil ID
	p1 p2 p3 p4	; product ID
	el e2	; engine software version
	s1 s2	; setup software version
\$F7		-

p1 through p4 represent four hexadecimal numerals which constitute the product ID. p1 is the major product heading (150 FS, 250, or 1000), and p2 through p4 distinguish the various models within the major headings. The product code for a 1000 GX, for example, would be: p1 = \$64; p2 = \$01; p3 = \$04; p4 = \$00. The table below shows the codes for all Kurzweil products with SysEx capabilities.

ID#				Product
\$15				K150
\$19				K250 or 250RMX
\$64	\$01	\$00	\$00	1000PX
	\$01	\$01	\$01	PX Plus
	\$01	\$02	\$00	1000SX
	\$01	\$03	\$00	1000HX
	\$01	\$04	\$00	1000GX
	\$01	\$05	\$00	AX Plus
	\$01	\$05	\$02	1200 Pro
	\$02	\$01	\$00	K1000 SE
	\$03	\$01	\$01	1000EX
	\$04	\$01	\$00	EGP
<i>p1</i>	<i>p2</i>	р3	p4	

e1, e2, s1, and s2 represent the hexadecimal values indicating the software version of the 1000. e1 and e2 indicate the engine (operating system) software, which is common to all 1000 Series products. s1 and s2 indicate the setup software. It is the setup software which distinguishes a GX from a PX, etc. For both engine and setup software, the first numeral is the major version number, and the second is the subversion, if any. For example, version 1.0 would be represented as $01 \ 000$. Version 2.14 would be $02 \ 000$.

Remote Front Panel

The remote front panel messages allow control of the 1000 series over MIDI. The format of the message is

\$F0 \$07 <device ID> \$64 \$01 <buttons> \$F7

where \$64 is the major product ID (i.e., 1000 series) and <buttons> are any number of button codes:

Code	Button	
\$00	digit '0'	(K1000 only)
		-
\$09	digit '9'	(K1000 only)
\$10	play/edit	
\$11	mode/layer	
\$12	chan/menu increment	
\$13	chan/menu decrement	
\$14	chan/menu incr & decr (double press)	
\$15	prog/param increment	
\$16	prog/param decrement	
\$17	prog/param incr & decr (double press)	
\$18	value increment/yes	
\$19	value decrement/no	
\$1A	value incr & decr (double press)	
\$1B	enter	(K1000 only)
\$1C	store	(K1000 only)
\$20	bank 'A'	(K1000 only)
\$21	bank 'B'	(K1000 only)
\$22	bank 'C'	(K1000 only)
\$7F	send display	

Whenever the special "send display" button (\$7F) is sent, the K1000 responds with

\$F0 \$07 <device ID> \$64 \$02 <display text> \$F7

where <display text> is the contents of the K1000 display as ordinary ASCII characters.

Dump Request Message

This message may be used to request a dump of any object or group of objects in the 1000's memory. The type and ID number select the object to be dumped. A type of \$00 means all types and and ID number of \$00 means all objects of the requested type. If the RAM-flag is true (i.e., not zero) only objects stored in non-volatile RAM will be dumped. For example, to request a dump of all RAM based programs, use:

\$F0 \$07 <device ID> \$64 \$03 \$00 \$50 \$00 \$00 \$01 \$F7

To request a dump of the Master Parameter Table, use:

\$F0 \$07 <device ID> \$64 \$03 \$00 \$42 \$00 \$00 \$01 \$F7

To request a memory dump (User Objects and RAM), use:

\$F0 \$07 <device ID> \$64 \$03 \$00 \$42 \$00 \$10 \$01 \$F7

Channel Setup Message

This message may be used to set the MIDI mode (Omni, Poly, or Multi) and to enable or disable specific MIDI channels. If <chan-a> (or subsequent) = \$00, then it signals a mode change. A value of \$01 for <mode-a> (or later) indicates Omni mode, \$02 is Poly, and \$03 is Multi.

If <chan-b> or subsequent is \$01 through \$10 (16), it is read as a MIDI channel number. In this case, the following <mode> byte value determines whether that MIDI channel is active. \$00 enables the channel, and \$01 disables it. For example, to put the instrument in Multi mode, with channels 1 thru 4 enabled, use:

\$F0	\$07	<device< th=""><th>ID></th><th>\$64</th><th>\$04</th><th>\$00</th><th>\$03</th><th>; multi mode</th></device<>	ID>	\$64	\$04	\$00	\$03	; multi mode
	\$01	\$00 \$02	\$00	\$03	\$00	\$04	\$00	; enable 1-4
	\$05	\$01 \$06	\$01	\$07	\$01	\$08	\$01	; disable 5-8
	\$09	\$01 \$0A	\$01	\$0B	\$01	\$0C	\$01	; disable 9-12
	\$0D	\$01 \$0E	\$01	\$0F	\$01	\$10	\$01	; disable 12-16
\$F7								

Kurzweil 1000 Series Binary Data Transfer Protocol

Kurzweil Music Systems, Inc.

2nd Edition: April '88 1st Edition: February '88

Notes on 2nd Edition

The 2nd edition of this document corrects an error in the description of the data packet checksum. The <u>checksum is</u> <u>computed over the data bytes only</u> and does not include the packet number and size as the previous document described.

Introduction to the 1st Edition

These notes describe a simple(?) mechanism for reliable binary (eight bit) data transmission over MIDI. The implementation is a two level approach; the transmission of binary information is separated from the purpose (e.g., file transfer) of the information.

First, a basic packet level protocol is defined which allows for bidirectional exchange of binary (eight bit) data packets with error checking and re-transmission. This protocol features a synchronization sequence which allows both parties to negotiate details such as transmission speed (to allow for higher-than-MIDI baud rates), packet size and number of outstanding packets (for machines with large buffers).

Within the context of the packet protocol, higher level protocols may then be defined to implement various forms of data transfer (remote file systems, interactive streams, etc).

This protocol, as described, is currently implemented on the new 1000 series of rack-mount MIDI expanders as well as the new K1000 keyboard. A description of the 1000 data transfer messages is also included, to illustrate how the packet protocol may be used.

The Packet Level

The following description assumes a bidirectional link (closed loop) between the two parties. There is a brief discussion at the end of this section on how the protocol behaves in an open loop situation.

Message Format

All messages are transmitted as standard Kurzweil system exclusive messages of the form:

\$F0 \$07 <dev-ID> <mesg-ID> <data ...> \$F7

Normally, in Kurzweil system exclusives, the <mesg-ID> byte is actually a product ID. Since this protocol is intended to apply to a variety of products, we use a certain range of the number space for message ids:

\$78-\$7BSync Messages (levels 0 thru 3)\$7CData Packet\$7EData Packet acknowledged (ACK)\$7FData Packet not acknowledged (NAK)

The Hand Shake

To exchange data packets (in either direction), the parties at either ends of the MIDI cable must be in sync. Not physical sync, since we are transmitted data asynchronously, but logical sync, in which each party begins in the

same state. The synchronization process consists of exchanging handshake messages which specify the desired transmission parameters (speed, packet size, etc.). These messages have the form

\$F0 \$07 <dst-ID> <syncN> <src-ID> <xSpeed> <nPacks> <pSizeH> <pSizeL> \$F7

The elements of this message are

- **dst-ID** The device ID of the destination. SYNC0 (\$78) messages may be sent with a device ID of 127 as a general request for sync.
- syncN The message ID (\$78 thru \$7B), which includes the party's current synchronization state.
- src-ID The device ID of the transmitter (0 thru 126).
- **xSpeed** The desired transmission speed (1x, 2x, 4x, etc.).
- nPacks The maximum number of outstanding packets (1 thru 127).
- **pSize** The maximum number of eight bit bytes that will be transmitted in a packet (a 14 bit value sent as two seven bit values).

All sync sequences begin at level 0 with both parties transmitting at standard MIDI speed. A party can transmit SYNC0 messages to actively make a connection or it can wait passively for the arrival of a SYNC0 message. When either party receives a SYNC0 message, it should respond by transmitting a SYNC1 message. Here, the transmission parameter negotiation takes place: each party begins by declaring its maximum capability and then lowering its parameters in response to SYNC1 messages from the other party, until a common denominator has been achieved. Then each party switches to level 2. If a speed change is required because the parties have agreed on a higher transmission rate, they switch speeds before transmitting their level 2 messages. Once the parties exchange identical SYNC2 messages, they switch to level three. Once each party has received a valid SYNC3 message, synchronization has been achieved and the exchange stops. Now the parties are able to exchange data packets.

Data Packets

Each data packet message has the form:

\$F0 \$07 <dst-ID> \$7C <src-ID> <pktNum> <pSize> <data ...> <chkSum> \$F7

The elements are

- **dst-ID** The destination device ID (0 thru 126).
- **src-ID** The source device ID (0 thru 126).
- pktNum The packet number. Packet numbers will sequence from 0 to 127.
- **pSize** The number of <u>eight bit bytes</u> contained in the packet (two seven bit values concatenated, MSB sent first). Must be between zero and the agreed upon maximum. The actual number of data bytes in the message will be larger (see below).
- **data** The binary data, transmitted in a seven bit format (see below).
- **chkSum** A fourteen bit check sum accumulated <u>over the data bytes only</u>. The check sum is calculated by rotating the 16 bit sum left one bit and then adding each seven bit value. Only the low seven bits of each byte are transmitted in the packet (i.e., the sign bits are dropped), MSB first.

Binary Data Transmission Format

The simplest transmission scheme is "nibble-izing," sending each data byte as two four bit values. This is the easy to read but it doubles the transmission time. The most efficient packing format (short of some exotic compression scheme like Huffman encoding) is to send the low seven bits of each byte, with every seven data bytes followed by one byte containing the seven sign bits. Thus, the seven binary data bytes

AAAAaaaa BBBBbbbb CCCCcccc DDDDdddd EEEEeeee FFFFffff GGGGgggg

are transmitted as

0AAAaaaa 0BBBbbbb 0CCCcccc 0DDDdddd 0EEEeeee 0FFFffff 0GGGgggg 0ABCDEFG

If the number of data bytes is not a multiple of seven, a short chunk is transmitted. E.g., if three bytes are left over

```
AAAAaaaa BBBBbbbb CCCCcccc
```

they are transmitted as

0AAAaaaa 0BBBbbbb 0CCCcccc 00000ABC

This scheme requires that the receiver know the length of the stream, either in logical size (i.e., the number of eight bit bytes) or physical size (the number of seven bit bytes). In general, to transmit N eight-bit bytes requires N + (N + 6)/7 seven bit bytes (assuming truncating integer division). Conversely, receiving M seven bit bytes yields 7 * (M / 8) + (M mod 8 - 1) eight bit bytes.

Since the packets are delimited by the system exclusive message, their length is self defined. Thus, within the packet itself, we include <u>the size as the number of eight bit bytes</u> contained in the data. While this may seem counter-intuitive, we believe it to be a more convenient number since it represents the size of the buffer into which the data is unpacked (see the attached code samples).

Response to Data Packet

\$F0	\$07	<dst-id></dst-id>	\$7E	<src-id></src-id>	<pktnum></pktnum>	\$F7	(ACK)
\$F0	\$07	<dst-id></dst-id>	\$7F	<src-id></src-id>	<pktnum></pktnum>	\$F7	(NAK)

Successfully received packets are ACKed. If an error or timeout occurs during packet reception, the receiving party will transmit a NAK message. Upon receiving a NAK, the transmitting party will re-transmit the incorrect packet.

Open Loop Behavior

Timeouts during a sync sequence will cause the transmitting party to reduce its requirements to a minimum (lowest speed, one packet, 128 byte packet size) and begin data transmission. Since it knows that the other party did not respond to sync, it can transmit packets at a default rate, without waiting for timeouts on ACKs.

Data packets received by party which is not in level three sync are ignored. Thus, a receiver which may operate in either mode needs some kind of front panel control to enable the reception.

Bypassing Sync

It is also possible to allow a receiver to power up in level 3 sync state (given default parameters of normal MIDI speed, 1 outstanding packet and a reasonable buffer size, say, 128 bytes). This would allow it to transmit and receive data packet messages without going thru the handshake sequence.

Message Summary

State	Message	Condition	Response	Newstate
SYNC0	SYNC0 other		SYNC1 none	SYNC1
SYNC1	SYNC0 SYNC1 SYNC1 other	mismatch match timeout	SYNC1 SYNC1 SYNC2 none	SYNC2 SYNC0 SYNC0
SYNC2	SYNC2 SYNC2 SYNC3 SYNC3 other	match mismatch match mismatch timeout	SYNC3 SYNC0 SYNC3 SYNC0 none	SYNC3 SYNC0 SYNC3 SYNC0 SYNC0
SYNC3	SYNC2 SYNC3 DATA DATA ACK NAK other	match correct error rcv timeout NAK limit exceeded xmt timeout retry limit exceeded	SYNC3 none ACK NAK NAK transmit next re-transmit current re-transmit SYNC0	SYNC0 SYNC0 SYNC0

K1000 Data Transfer Protocol

The higher level protocol consists of a stream of messages which exist at a level above the packet protocol, which simply acts as a delivery vehicle. In the K1000 series expanders, this higher level protocol implements a simple remote file system which allows a remote computer to manipulate the contents of the K1000's object heap memory.

Message Format

100 message-id data...

Each message begins with its protocol ID byte (in this case, 100, the product ID for the K1000 series) and a message ID. The format of the remaining data is determined by the message type. Messages are divided into two categories, requests and responses. For convenience, request message types are even numbers and the response type for any message is its request type + 1.

In the following, all messages are in eight-bit binary! They must be formatted, then transmitted using the packet protocol described above. Also, the notation [n] indicates the size of the item in bytes. If omitted, the size is one byte.

Directory Request/Response

100 0 type idno 100 1 type idno size[4] zone[4] name[N]

Used by the remote device to request information about objects contained in the K1000's memory. An idno of zero means all objects of a given type. Size gives the size of the object in bytes, zone identifies the heap space in which the object resides, and name is the name of the object (if it has one) as a NUL-terminated string.

The when a request for info about all objects of a given type is received, the K1000 responds with a series of messages. The last of these is a null message (idno of zero) to indicate the end of the list.

Dump Request/Response

100 2 type idno size[4] offset[4] 100 3 type idno size[4] offset[4] data[N]

Used to read objects (or portions of objects) from the K1000's memory. A single read request will elicit multiple responses if request size is larger than the available data size in the message.

Create New Object

100 4 type idno size[4] 100 5 type idno size[4] zone[4]

Used to create new objects in the K1000's memory. If the size item in the response message is zero, the object could not be created and the zone item is an error code. Otherwise, zone indicates the heap zone name in which the object will reside. New objects may have the same ID as ROM objects; in this case the RAM object will "hide" the ROM object.

Write Request/Response

100 6 type idno size[4] offset[4] data[N] 100 7 type idno size[4] offset[4]

Used to write data into objects (or portions of objects). When writing into a newly created object, the series of write requests should be terminated by a zero length write message (i.e., an EOF signal).

Delete Object

100 8 type idno 100 9 type idno

Used to delete objects from the K1000's memory. Deleting a RAM object which was overriding a ROM object of the same ID will "uncover" the ROM object. Thus, if one is maintaining a directory of K1000 objects, the delete request should be followed by an info request to determine if a ROM version of the object exists.

Kurzweil 1000 Series Object Overview

Kurzweil Music Systems, Inc.

1st Edition: February'88

Objects In General

The ROM and RAM memory of the 1000 series is organized as a collection of objects which are identified by a unique type and ID number. Any object may be up or downloaded by using the binary data transfer protocol (described in a separate document). Besides programs (aka patches) other object types exist (e.g., LFO shape tables) and any ROM object may be replaced by a RAM version.

Object Format

The first two bytes of each object contain the type and ID number of the object. E.g., in a program, the type is progType and the ID number is the the program number (typically one greater than the MIDI program number). While some objects have a fixed size (in which the format of the remaining data is determined solely by the type of the object) most objects are variable sized; the second word of the object is the size of the object in bytes. The size may be odd but the software assumes that all objects begin on even boundaries and pads the size to an even number of bytes.

Each variable sized object consists of 1) a header whose size is determined by the object type, 2) an optional name (presence determined by type), NUL-terminated and padded to an even number of bytes and 3) the extension data whose size is just the size of the object less the size of the fixed header and the name (if present). The contents of the extension data is arbitrary; for certain objects (programs and layers) the extension data contains more objects (which may be of fixed or variable size). Thus, editor/librarian software must be prepared to deal with a hierarchy of nested objects.

Programs, Layers, Etc.

The most visible user object is the **program**, which is basically a shell which contains the layer objects (up to four in the current 1000 series) as well as objects which define global control sources (LFOs and ASRS). The information in the program header is small, consisting of some voice allocation parameters (stealing and polyphonicity limit) and an alternate MIDI program number.

The majority of the information needed for starting notes is contained in the **layer** object. Besides the stuff in the layer header, the layer's extension data contains objects which define the local control sources (LFOs, ASRs and envelopes).

Many of the items in objects are ID numbers of other objects; others are enumerations where the actual value of a parameter is obtained by using the parameter as an index into a table. As an example, lets look at the description of the LFO parameter block:

/*	
* LFO parameter	
*/	
typedef struct {	
uByte lfob_type;	/* = lfoType */
uByte lfob_idno;	/* = 1 or 2, 8 or 9 for globals */
uByte lfob_rfu;	
uByte lfob_flags;	/* initial phase, etc */
uByte lfob_shape;	/* ID# of shapeType object */
uByte lfob_rtCtl;	/* rate control (enum table #1) */
uByte lfob_rtMin;	/* min rate (enum table #4) */
uByte lfob_rtMax;	/* max rate (enum table #4) */
} LFOB;	

In this structure the waveshape of the LFO is determined by the lfob_shape parameter, which is the ID# of an LFO shape table (i.e., a shapeType object). Thus to display the name of the waveshape (e.g., 'Sine' or 'Rising Saw') one needs a list of shapeType ID's and names. Similarly, the LFO's rate control and range are obtained by indexing into the appropriate master tables (tables #1 and #4).

Most stuff within the layer block is fixed size, with two exceptions: the envelopes and two tables (ID numbers 17 and 18) used by the high level effects (absent if the program uses modular effects). The envelope header just contains the number of segments in each section (attack and release) with the segments themselves immediately following the header.

Note: although the on-board editor allows only eight segments per section, the note control software supports up to 128 segments per section. However, trying to edit (in the 1000) an envelope with more than eight segments in a section will probably cause the editor to crash!

Objects within the program or layer are parsed in sequential order. Scanning stops at the end of the data or when an invalid object is detected. Valid objects which are not recognized by the note control software are ignored (e.g., the two tables mentioned above are used only by the editor). If two objects have the same ID number, the last one seen is the one that is used.

The ID numbers of the various objects are significant. E.g., each layer may have an LFO #1 and/or #2. LFOs with IDs other than these are ignored (although future instruments may support more LFOs per voice). Global LFOs, which are contained in the program data, have ID numbers beginning with nine (e.g., gLFO 1 is really LFO #9).

Note: Early on in the development, we decided that any local object (i.e., with an ID number of 1 thru 8) appearing in the program data would apply to all layers (unless overridden by a specific object appearing in the layer data). We haven't actually done this yet, but will probably do so in a future release of the software to allow limited form of data compression. Be prepared!

Within programs and layers, table ID numbers 1 thru 63 are reserved (e.g., in the next release, a special table ID may be designated to contain MIDI data to be transmitted on program change). Other numbers may be used, e.g., to add comments, copyright info, etc.

Keymaps and Sound Blocks

Each layer object contains the ID of a **keymap**; this object is a variable size mapping table used to convert MIDI key numbers and attack velocities into pitch and loudness and sample selection. Each keymap in turn refers to one or more **sound blocks**, which are collections of sound file headers (which contain the low level information needed to play back the samples). Since these are variable-sized structures with several optional sections, a diagram of the overall layout is included.

The variable data portion of a keymap consists of one or more byte per key arrays. These include one or two bytes of optional tuning information, optional volume adjust, optional sound block IDs and sound file IDs. Keymaps are also organized into multiple timbre levels which are automatically selected by key velocity.

Note: Currently, a keymap always contains a byte per key array of sound file header numbers. A future optimization will allow for special keymaps which reference a single soundfile (e.g., an attack noise) by storing the sound file ID in the headers

The sound blocks contain lists of sound file headers. These are the actual descriptions of the samples, along with the so-called "natural envelopes" needed for proper playback.

Other Objects

The actual waveshapes generated by the LFOs are stored as shapeType objects. All incoming MIDI program numbers are converted to internal program numbers using MIDI program lists (mlistType). Intonation tables (itblType) allow tuning of the scale away from equal temperment. Velocity maps (vmapType), in combination

with several of tables described below, determine the mapping of MIDI key velocities into loudness and control sources.

Demo Song Objects

(excerpts from the V5 Software addendum manual)

A RAM based SONG (Demo) object is basically a MIDI File, Type 0, with a 1000 Series object header prepended to it. Demo songs may be loaded, named, renumbered, or removed with ObjectMover. A separate program is needed to turn MIDI files into object files.

There may be more than one Demo song in an object file, in which case, there would be multiple song headers. All song objects must be word aligned. The Demo player will play them in the order of their resource IDs, in a repeating cycle.

It is recommended that your program remove, or truncate, text meta-events from the data stream (to save RAM space). Only the tempo meta-event is interpreted by the 1000.

The block size in the object header is the size of all the objects in file, negated. The blockSize must include everything from itself to the end of file, so you will calculate DO_blockSize like this:

demoFile->DO_blockSize = -(fileSize - 32);

The object size itself is calculated in a similar way. Object size should include all data from the type and id fields, to the end of your song. Because this is a 16 bit field, there is a 64K maximum size for demo objects.

The tempo field (DS_tempo) is a precalculated clock increment providing the initial tempo of the song. This is a 32 bit field which is added to the Demo clock every 2 milliseconds. The Demo clock counts off 1/480 of a quarter note times, with a 16 bit fraction. Your program can calculate the clock increment like this:

myDemo->DS_tempo = (long)bps * 1048L;

Where 'bpm' is the desired "beats per minute" for your song. If you are working from the MIDI file's "microseconds per beat" value, the formula becomes:

myDemo->DS_tempo = (60000000 / uspb) * 1048L;

Following the song header, comes the name field. This name may be any length (up to 64 chars) and must be null terminated. The MIDI File song data starts on the next even address after that.

Tables

Table objects are actually miscellaneous, one-of-a-kind objects. All tables are variable sized, unnamed objects; the format of the extension data is determined by the particular table's ID number. The following is a list of some of the more interesting tables organized by ID number:

Description

- 1 Control Source Enumeration Table gives name, type and ID# for both MIDI and internal control sources.
- 2 Envelope/ASR Time Enumeration. Determines the actual times for envelope and ASR segments. Non-linear.
 3 Enumeration of note start delays. Non-linear.
- 4 Enumeration of LFO rates. Non-linear. Contains offsets into table #27.
- 5 Enumeration of Envelope Scale Factors. Contains offsets into table #6. Uses 5% resistor value scale.
- 6 Logarithmic Multiplier Table used to scale envelope rates. Table #5 contains offsets into this table.
- 11 MIDI control number map. Incoming MIDI control change messages have their control numbers mapped thru this table. Allows re-assignment of controls.
- 16 Master parameter data. Contains most everything that is editable in the master menu. Snapping a copy of this object captures the entire state of the machine (MIDI channel and mode, program assignments, etc).

- 17 Object mapping table (contained in program only). Used by the high-level effects editor to map pseudo parameters to real parameters.
- 18 Pseudo parameter table (program only). Contains the actual values of the high-level pseudo parameters.
- 21 Key velocity to loudness curve (combined with velocity map).
- 22 Key velocity to control source value curve (combined with velocity map).
- 23 Mono/Poly pressure to control value curve. Default is linear.
- 24 Volume control table (MIDI control value to loudness). Non-linear.
- 25 Balance control table. Equal power crossfade curve.
- 27 LFO phase increments. Table #4 contains offsets into this table.
- 28 Enumeration of bi-polar envelope segment values. Converts percentages into output levels. Linear.
- 29 Enumeration of amplitude envelope segment values. Converts percentages into loudness levels. Non-linear.

Note: The master parameter block, which is currently table #16, is soon to become a distinct, named object. Thus, the instrument will be able to store multiple sets of master parameters. We haven't decided exactly how to do this, yet, so stay tuned for more info...

K1000 Object Types

Type#	Hex	Description	Named?	
66	\$42	Master Table		
68	\$44	LFO Shape	yes	
69	\$45	Sound Block	yes	
70	\$46	Keyboard Map	yes	
71	\$47	MIDI Program List	yes	
72	\$48	Edit Menu Definition		
73	\$49	Edit Menu Group		
74	\$4A	Edit Menu Entry List		
75	\$4B	Intonation Table	yes	
76	\$4C	Compiled Effects Descriptor	yes	
77	\$4D	(Rcv) Velocity Map	yes	
78	\$4E	Rcv PressMap	?	v5
79	\$4F	Editor Descriptor		
80	\$50	Program Data Block	yes	
81	\$51	Layer Data Block	yes	
82	\$52	ASR Parameter Block		
83	\$53	LFO Parameter Block		
84	\$54	ENV Parameter Block		
85	\$55	EFX Parameter Block		
86	\$56	INVNEG Parameter Block		
87	\$57	MXR Parameter Block		
91	\$5B	Demo Song	yes	v5
94	\$5E	Program List	?	v5
95	\$5F	Bin Map	?	v5

K1000 Database Master Tables

ID#	Description	Where	
1	Control Source Enumeration	EROM	
2	ENV/ASR Time Enumeration		SROM
3	Delay Time Enumeration		SROM
4	LFO Rate Enumeration		SROM
5	ENV Ctl Scale Enumeration		SROM
6	ENV Ctl Log Multiplier		SROM
7	Playback Rate Compensation Table (2)		SROM
8	Edit Parameter ID Table	EROM	
9	Edit Menu Position Table	EROM	
10	Editor Default Object Table	EROM	
11	MIDI Control Mapping Table	EROM	
12	Front Panel Button Table (4,5)		SROM
13	Diagnostic Tables (4)		SROM
14	Product Configuration Table (3,4,6)	EROM	SROM
15	Arnold Configuration Table (1)		SROM
16	Prototype Master Data Block (5)		SROM
21	Velocity to Loudness Curve		SROM
22	Velocity to Control Source Curve		SROM
23	Pressure to Control Source Curve		SROM
24	MIDI Volume Control Table	EROM	
25	Equal Power Attenuation Curve	EROM	
26	Playback Rate Table	EROM	
27	LFO Phase Increment Table	EROM	
28	ENV Value Enumeration	EROM	
29	Amp ENV Value Enumeration	EROM	
30	Amp ENV Attack Shape Curve	EROM	

Notes:

- 1. Determines sound engine configuration and bandwidth.
- 2. Specific to sound engine bandwidth.
- 3. Determines UART and front panel type.
- 4. Specific to product.
- 5. Specific to front panel.
 6. Determines initial settings after hard reset.
 7. Contains product and version ID numbers.

/* * */	Types.h	Tues	day	, Febrı	uary 23, 1988 7:04 PM
/* * ob */ enum {	<pre>blockType=64, indexType, tableType, shapeType=68, soundType, keymapType, mlistType, menuType, melType, itblType, fxType, vmapType, pmapType, editType=79, progType, layerType, asrType, lfoType, efxType, invType, songType=91,</pre>	· / / / / / / / / / / / / / / / / / / /	666689a123456778901234567145ee	\$ 442456789ABCDEF01234567BEF a t	 ENV Parameter Block */ EFX Parameter Block */ INV/NEG Parameter Block */ MXR Parameter Block */ Demo Song (named), V5 */ Program List, V5 */ Bin Map, V5 */
#defir	e baseTwoe block	Tune			

#define baseType blockType

#define globidno 8 /* base id # for globals */

Objects.h Tuesday, February 23, 1988 7:35 PM * Database definitions for K1000 Database Objects * To insure future compatability, all RFU items must be zero! typedef char sByte; /* signed byte */ /* unsigned byte */ typedef unsigned char uByte; typedef int sWord; /* signed word (a 'short') */ typedef unsigned int /* unsigned word (a 'short') */ uWord; #define /* # dynamic range marks */ nDYNAM 8 * generalized data block header */ typedef struct { uByte gdb_type; uByte gdb_idno; sWord gdb_size; } GDB; * extended data block header */ typedef struct { uByte xdb_type; uByte xdb_idno; sWord xdb_rfu; long xdb_size; } XDB; * Master data block */ typedef struct { uByte mdb_type; /* tabletype */ /* 16 */ uByte mdb_idno; sWord mdb_size; /* MIDI mode */ /* basic MIDI channel # 1...16) */ uByte mdb mode; uByte mdb_chan; /* sys-ex device ID 0...126 */
/* displayed channel # 1...16 */
/* ID of vmapType object */ uByte mdb_devI0; uByte mdb_dchan; uByte mdb_velMap; uByte mdb_ctlMap; uByte mdb_flags; uByte mdb bflags; sByte mdb_tune; /* master tune (± cents) */ sByte mdb_trans; uByte mdb_intTab; /* master transpose (± semi-tones) */
/* ID of itabType object */
/* intonation reference key */ uByte mdb_refKey; /* transmit program change map */ uByte mdb_txPList; /* receive program change map */ uByte mdb_rxPList; /* bin bank program map (K1000 only) */ uByte mdb_bbPList; uByte mdb_bbentry; /* current entry */ uByte mdb_editPos[4]; sByte mdb_pwRange; /* global pitch wheel range (± QT) */ /* global soft pedal range (± dB) */ sByte mdb_spRange; sByte mdb_dynam; /* additive dynamic range adjust (±dB) */ uByte mdb_rfu1; /* software version stamp */
/* programs/channel */ uByte mdb_version[4]; uByte mdb cproqs[16];

```
* local keyboard control assignments (K1000 only)
          */
                                                 /* sustain pedal */
/* other pedal */
        uByte mdb_pedal1;
        uByte mdb_pedal2;
                                                /* mod wheel - up */
/* mod wheel - down */
/* data slider */
        uByte mdb wheelUp;
        uByte mdb_wheelDn;
        uByte mdb_slider;
        uByte mdb_rfu2;
        uByte mdb_rfu3[10];
        /*
         * more per channel stuff
         */
                                                 /* flags */
/* volume adjust (±dB) */
        uByte mdb cflags[16];
        sByte mdb_volume[16];
sByte mdb_stereo[16];
uByte mdb_plimit(16];
                                                 /* stereo position */
                                                /* poly limit */
/* low/hi MIDI keys */
        uByte mdb_range[16][2];
} MDB;
/* Flag definitions for mdb_flags */
                                                 /* force monophonic output */
#define mdb_monoOut 0x01
#define mdb_monoduc0x01#define mdb_ignNOff0x02#define mdb_mRefKey0x04#define mdb_parEdit0x08#define mdb_confirm0x10#define mdb_echoPChg0x20
                                                 /* ignore MIDI all notes off */
                                                 /* MIDI intonation ref key */
/* MIDI parameter editing */
                                                 /* ~confirm deletes */
                                                 /* echo program changes */
/* steal same note */
#define mdb_stealSame 0x40
 * Flag definitions for mdb_bflags
 */
                                0x01/* button repeats */0x02/* button repeat rate (slow/fast) */0x04/* button acceleration */
#define mdb_btnRept 0x01
#define mdb_btnRate 0x02
#define mdb_btnAccl 0x04
#define mdb_btnAccl
 * Flag definitions for mdb_cflags
 * /
#define mdb_volDis0x01#define mdb_panOver0x02#define mdb_rngOver0x04
                                              /* volume disabled */
/* stereo pan override */
/* MIDI kbd range override
 * program data block
 * just a shell to enclose the layer definitions
 * /
typedef struct {
        uByte pdb_type;
uByte pdb_idno;
        sWord pdb size;
        uByte pdb_rfu1;
                                           /* output program */
/* assignment algorithm */
/* polyphonicity limit */
        uByte pdb_midiProg;
        uByte pdb stealOpt;
        uByte pdb phLimit;
        uByte pdb_rfu3[8];
} PDB;
 * layer data block (named)
 * contained in program data
 */
typedef struct {
        uByte ldb_type;
uByte ldb_idno;
                                                 /* = layerType */
        sWord ldb size;
        uByte ldb_keymap; /* ID of keymapType object */
uByte ldb_lokey; /* lowest MIDI key # */
```

/* highest MIDI key # */ uByte ldb_hikey; /* transpose (± semi-tones) */ sByte ldb_trans; /* detune (± cents) */ */ /* delay (enum table 23) */ /* volume adjust (±dB) */ sByte ldb_dtune; uByte ldb_delay; sByte ldb_volume; /* stereo position */ sByte ldb_stereo; /* stereo position */
/* compiled effect ID */
/* compiled effect linkage */
/* key state flags */
/* effects flags */
/* enable switch (enum table #1) */
/* alt attack switch (enum table #1) */
/* velocity trigger stuff */
/* dynamic range (dB) */
/* dynamic range (dB) */
/* balance control (enum table #1) */
/* soft pedal range (±dB) */
/* pitch wheel range (± quarter-tones) */
/* used by compiled effects */ uByte ldb_effect; uByte ldb_nLink; uByte ldb_kflags; uByte ldb_xflags; uByte ldb_enable; uByte ldb_legato; uByte ldb_vflags; uByte ldb_dynam; sByte ldb_keyTilt; uByte ldb_balCtl; sByte ldb_spRange; sByte ldb_pwRange; uByte ldb_lastOut; uByte ldb_rfu[7]; } LDB; * ldb_kflags #define ldb_ignRels0x01#define ldb_ignSust0x02#define ldb_ignSost0x04#define ldb_ignSusp0x08 /* ignore key release */ /* ignore key release */ /* ignore sustain pedal */ /* ignore sostenuto pedal */ /* ignore suspend pedal */ * ldb_xflags */ /* pitch wheel disabled */
/* pitch bend only key down */
/* volume control disabled */ #define ldb_pwlDis
#define ldb_pwlKey 0x010x02 #define ldb volDis 0x08/* touch sense disabled */ */ 0x10 #define ldb touchDis /* balance control reversed */ #define ldb_balRev 0x20 * ldb_vflags */ 0x07 0x08 0x70 /* vtrig 1 level (fff -> ppp) */ /* vtrig 1 sense */ /* vtrig 2 level */ #define ldb_vt1Level #define ldb_vt1Sense
#define ldb_vt2Level 0x70/* vtrig 2 sense */ #define ldb_vt2Sense 0×80 * Amplitude control patch block * / typedef struct { uByte type, idno; uByte rfu1[2]; /* = efxtype,1 */ /* mod source (enum table #1) */
/* mod depth (enum table #1) */
/* min depth (dB) */
/* max depth (dB) */ uByte amInput; uByte amDepth; sByte amMin , sByte amMax; uByte rfu2[8]; } AFXB; * Pitch control patch block * / typedef struct PFXB { /* = efxType,2 */ uByte type, idno; uByte rfu1[2]; uByte fmInput; /* mod source (enum table #1 */ uByte fmDepth; /* mod depth (enum table @1) */

```
/* min depth (cents) */
/* max depth (cents) */
         sByte fmMin;
         sByte fmMax;
         uByte rfu3;
                                                    /* detune control (enum table #1 */
/* min value (cents) */
/* max value (cents) */
         uByte dtCtl;
         sByte dtMin,
         sByte dtMax;
         uByte rfu2[4];
} PFXB;
 * Envelope control patch block
 */
typedef struct ENCB {
         uByte type, idno;
uByte rfu1[2];
                                                       /* = efxType,3 */
         struct {
                  uByte rfu;
                                                   /* control (enum table #1) */
/* min rate (enum table #5) */
/* max scale (enum table #5) */
                  uByte rateCtl;
uByte minScale
                  uByte maxScale;
         }
                                                       /* attack rate */
                  atCtl,
                                                       /* decay rate */
                  dtCtl,
                  rtCtl;
                                                        /* release rate */
} ENCB;
 * ASR parameter block
 */
typedef struct ASRB {
        uByte asrb_type;
                                                       /* = asrType */
         uByte asrb_idno;
         uByte asrb_flags;
                                              /* trigger input (enum table #1) */
/* delay time (enum table #2) */
/* attack time (enum table #2) */
/* sustain time (unused) */
/* release time (enum table #2) */
         uByte asrb_trig;
        uByte asrb_dtime;
uByte asrb_atime;
uByte asrb_stime;
         uByte asrb_rtime;
} ASRB;
 * asrb_flags
 * /
#define asrb_hold0x01#define asrb_rept0x02#define asrb_effect0x80
                                                   /* hold while trigger on */
/* repeat while trigger on */
 * LFO parameter block
 * /
typedef struct {
         uByte lfob_type;
                                                       /* = lfoType */
         uByte lfob_tidno;
uByte lfob_rfu;
uByte lfob_rfu;
uByte lfob_flags;
                                                     /* ID of shapeType object */
/* rate control (enum table #1) */
/* min rate (enum table #4) */
/* max rate (enum table #4) */
         uByte lfob_shape;
         uByte lfob_rtCtl;
uByte lfob_rtMin;
uByte lfob_rtMax;
} LFOB;
 * lfob_flags
 */
#define lfob_phase 0x03
#define lfob_effect 0x80
                                                       /* initial phase (0, 90, 180, 270) */
```

```
* envelope parameter block
 */
typedef struct {
      uByte envb_type;
                                       /* = envType */
      uByte envb_idno;
      sWord envb_size;
      uByte envb_naSegs;
                                       /* # attack segments */
/* # release segments */
      uByte envb_nrSegs;
      uByte envb_rfu[2];
} ENVB;
/*
 * envelope segments immediately follow the header
 *
      for all segments but last
 *
             level and time are enumerated
 *
 *
      last segment of each section is special:
      if (level > 0)
 *
 *
              jump back and repeat going forward
             level is segment # to jump to
time is repeat count (0 means infinite)
 *
 *
 *
 *
      else if (level < 0)
 *
             loop back and repeat (ie, backward, then forward)
             -level is segment # to stop at and change direction
 *
 *
             time is repeat count (0 means infinite)
 *
 *
      else (level == 0)
 *
             if (time > 0)
 *
                    time is decay/release time
 *
             else if (attack section)
 *
                    infinite sustain
 *
             else
 *
                    instant release
 *
 * /
typedef struct {
      sByte eseg_level;  /* level (enum table #28 or #29) */
uByte eseg_time;  /* time (enum table #2) */
} ESEG;
 * INV/NEG data block
 */
typedef struct {
      uByte invb_type;
                                        /* = invType */
      uByte invb_idno;
      uByte invb_rfu[2];
uByte inub_invlin;
uByte invb_inv2in;
                                        /* input (enum table #1) */
      uByte invb_neglin;
      uByte invb_neg2in;
} IHVB,
 * MXR data block
*/
typedef struct {
      uByte mxrb_type;
                                        /* = mxrType */
      uByte mxrb_ldno;
      uByte mxrb_rfu[2];
      uByte mxrb_in1A;
                                        /* input (enum table #1) */
      uByte mxrb_in1B;
```

```
uByte mxrb_in2A;
      uByte mxrb_in2B;
} MXRB;
/*
* keymap (named)
 * converts key number and velocity to sound file, pitch, and amplitude
 * /
typedef struct {
                                        /* = keymapType */
      uByte kmap_type;
      uByte kmap_idno;
      sWord kmap_size;
                                       /* low MIDI key # */
/* # keys - 1 */
/* offset to key data */
/* notes/octove */
(*
      sWord kmap_loKey;
      sWord kmap_nKeys;
sWord kmap_keyOff;
      sWord kmap_nOctv;
                                       /* pitch of lowest key */
/* cents/key */
      sWord kmap_pitch;
      sWord kmap_cents;
      uByte kmap_flags;
      uByte kmap_sound;
                                        /* ID of soundType object */
      uByte kmap_rfu1;
                                       /* # timbre levels */
      uByte kmap_level;
      uByte kmap_timbre[nDYNAM]; /* timbre level map */
      uByte kmap_rfu2[4];
} KMAP;
/*
 * kmap_flags
*/
                                      /* 1 means separate atten/key */
/* tuning type */
#define kmap_atten
                          0x01
0x0C
#define kmap_tune
/*
* the keymap data consists of byte/key arrays
 * switch (kmap_flags & kmap_tune)
 *
     case 0x00: no tuning adjust
     case 0x04:
                 relative byte (LSB only)
relative word (MSB/LSB)
absolute word (MSB/LSB)
 *
     case 0x08:
     case 0x0C:
 *
 * for (each timbre level) {
      if (kmap_flags & kmap_atten)
 *
 *
             amplitude adjust (1 byte/key) (8 * dB / 6)
 *
      if (kmap_sound == 0)
 *
            sound block ID (1 byte/key)
 *
      sound file header ID (1 byte/key)
 * /
* sound block (named)
*/
typedef struct sblk {
      uByte sblk_type;
uByte sblk_idno;
                                        /* = soundType */
      sWord sblk_size;
                                      /* base sound file ID \# */
      sWord sblk_hBase;
                                       /* # sound file headers - 1 */
      sWord sblk_nHdrs;
                                        /* offset to 1st header */
      sWord sblk_hdrOff;
      uByte sblk_rfu[6];
} SBLK;
/*
* block header is followed by NUL-terminated name
 * then by array of sound file headers
* /
typedef struct sfh {
      uByte sfh_rootKey; /* root MIDI key # */
```

```
uByte sfh_flags;
                                          /* amp adjust (dons) */
       sWord sfh_atten;
       sWord sfh_pitch;
                                          /* pitch at highest play rate */
       uByte sfh_rfu1[2];
       long sfh_start1;
long sfh_start2;
long sfh_loop;
                                           /* normal start sample address */
/* alternate start sample address */
                                          /* loop point sample address */
       long sfh_end;
sWord sfh_env1;
sWord sfh_env2;
                                          /* last sample address + 2 */
/* offset to normal envelope */
/* offset to alternate envelope */
       uByte sfh rfu2[4];
} SFH;
/*
 * header array is followed by natural envelopes
 * each segment is two words:
 *
       delta-a,delta-s
 * where delta-s is the segment length in samples
 * and delta-a is the attack/decay rate computed as
       delta-a = (2048 * delta-dB) / (6 * delta-s)
 *
 *
 * if the delta-a of the 1st segment is > 0,
 * a starting amplitude of 0 is assumed
 * otherwise, the amplitude starts at the maximum value
 \ast the last two segments are the decay and release segments \ast the delta-s for these must be 0
 * the delta-a should be computed using a delta-s which corresponds
 \ast to the \# of samples in 10 msec at the highest playback rate
 * for the decay segment, delta-a may be zero (for infinite sustain)
 */
 * LFO shape table (named)
 * header followed by name, then waveshape (256 words)
 * signed indexing is used so the offset is to the 0th entry
 * (ie, the middle of the table)
 * /
typedef struct {
                                          /* shapeType */
       char shapeTYPE;
       cmar shapeID;
sWord shapeSize;
sWord shapeOffs;
E;
                                          /* ID # */
                                          /* size (bytes) */
/* offset to center point (0th entry) */
} SHAPE;
/*
 * MIDI List (named)
 * used to map MIDI Program change numbers to real program numbers
 */
typedef struct {
    uByte mlistTYPE;
       uByte mlistID;
       sWord mlistSize;
                                  /* base MIDI program * */
/* # table entries - 1 */
/* offset to 1st entry (byte) */
       sWord mlistBase;
       sWord mlistN;
       sWord mlistOff;
} MLIST;
```

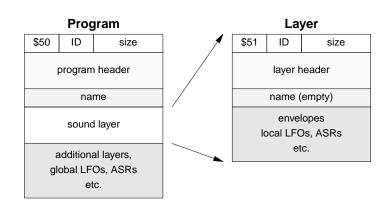
```
* Intonation table (named)
 */
typedef struct {
      uByte itblTYPE;
      uByte itblID;
sWord itblSize;
                                          /* [0] always 0 */
       sWord itblTbl[12];
                                           /* entries in cents rel to equal temp */
} ITBL;
 * Velocity map (named)
 */
typedef struct {
      uByte vmapTYPE;
       uByte vmapID;
       sWord vmapSize;
      uByte vmapVels[nDYNAM]; /* fff -> ppp */
} VMAP;
/*
* Data structure definitions for 1200 Demo objects
 * (from the V5 manual addendum)
* file type, first longword in file
 */
#define SROM
                            0x53524F4D
/*
* Demo object type and id declarations
*/
#define Demo1200
                            0x5B
#define DemoIDBase
                            1
* object file header, one per file
* /
typedef struct {
       long DO_type;
word DO_rfu[14];
                                          /* Demo (SROM) */
/* must be 0 */
                                          /* negative block size */
       long DO_blockSize;
} dFHdr;
/*
* song header, one per song
 */
typedef struct {
                                        /* 0x5B is a Demo song */
/* is (1..255) */
/* size of object */
      char DS_objType;
char DS_objID;
word DS_objSize;
                                          /* actual initial beat increment */
       long DS_tempo;
} demoSong;
/* name of the object goes here, before the song itself */
/* (must be null terminated, even number of bytes) */
```

```
/*
                           Tuesday, February 23, 1988 7:15 PM
       Tables.h
 * standard table header
 * /
typedef struct TBLHDR {
       uByte tbl_type;
uByte tbl_idno;
                                     /* = tableType */
       sWord tbl_size;
} TBLHDR;
/*
 * time enumeration entry
 */
struct enumTime {
                                     /* msec / 10 */
/* 32767 / ticks */
/* 32767 % ticks */
       uWord ticks;
uWord delta;
       uWord slop;
       uWord rfu;
};
/*
 * lfo rate enumeration
 */
struct enumRate {
    uWord roffs;
                                   /* offset into rate table entry */
/* hertz * 100 */
       uWord hertz;
};
/*
 * control source enumeration
 */
struct enumCtls {
       uByte type;
uByte idno;
                                 /* offset to name string
       sWord offs;
};
* envelope scale factor table header
* /
struct envScaleHdr {
                                     /* offset to 0th entry */
/* valid index range */
/* display value denominator */
       sWord base;
       sWord low, high;
       sWord dispNom;
}
 * table entry
 */
struct envScaleEnt {
    sWord multOff;
                                    /* offset into log multiplier table */
/* display value numerator */
       sWord dispNum;
}
```

/ *			
* table IDs			
*/			
enum {			
	* 1		control source enum */
enumTimeID, /	_		ENV/ASR time enum */
enumDelayID, /	* 3	-	layer delay enum */
enumRateID, /	-	-	LFO rate enum */
envScaleID, /	0		EMU rate scale factor anum */
logScaleID, /	•		log multiplier table */
prcTableID, /	* 7	-	playback rate compensation */
pidTableID, /*	-		parameter ID table */
mnpTableID, /	-		menu position table ID */
defTableID, /			default object table */
ctlMapID, /			MIDI control mapping table */
btnTableID, /			front panel button table */
diagTblID, /	-		diagnostic table */
productID, /			product ID/configuration */
	* 15		Arnold configuration */
masterID, /			initial master parameters */
omtID, /*			object mapping table (program only) */
pseudoID, /			Pseudo parameters (program only) */
attenMapID=21, /			velocity -> attenuation table */
velocMapID, /			velocity -> control value table */
pressMapID, /			pressure -> control value table */
volTableID, /			volume control table */
balTableID, /			balance control table */
playRateID, /*			playback rate table */
lfoDeltaID, /			LFO phase increment table */
envValueID, /	-		bi-polar EMU level enumeration */
ampValueID, /*			amplitude EMU level enumeration */
atkTableID, /	* 30	-	amplitude EMU attack table */
typeTableID			

};

1000 Series Program/Layer Structures



LF	0
\$53	ID
flags	
shape	rate
min	max
AS	SR
A \$ \$52	SR ID
\$52	ID

EN	ENV 54 ID size			
\$54	ID			
si	ze			
#aseg	#rseg			
level1	time1	attack		
•				
levelN	timeN			
level1	time1	release		
•				
levelN	timeN			

Program Header

	0	1	2	3
0	\$50	ID #	size (l	bytes)
4		output prog #	stealing option	poly limit
8				
12				

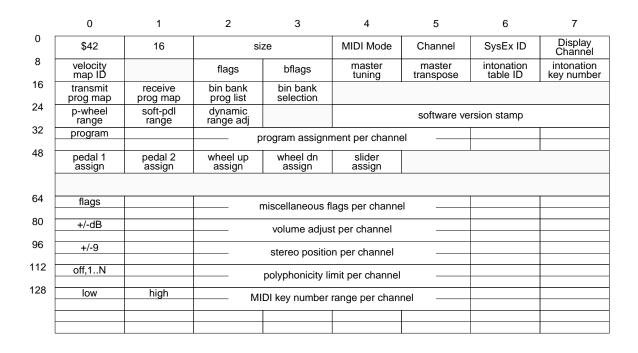
Layer Header

	0	1	2	3	
0	\$51	ID #	size (l	ze (bytes)	
4	keymap ID #	low key #	high key #	transpose	
8	detune	delay	volume	stereo	
12	compiled EFX ID#	compiled EFX link	k-flags	x-flags	
16	enable switch	alt start switch	v-flags	dynamic range	
20	keyboard tilt	balance control	soft pedal range	p-wheel range	
24	compiled EFX				

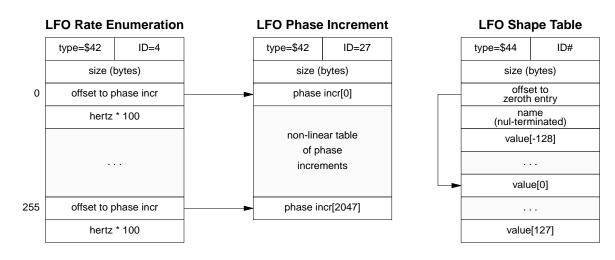
Layer Flags

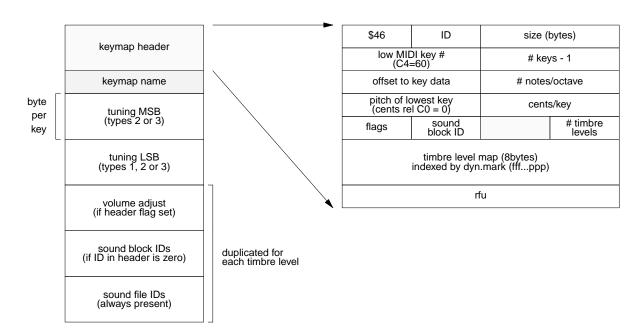
k-flags	-flags			ignore suspend	ignore sostenuto	ignore sustain	ignore release
x-flags		balance	touch	volume		p-wheel	p-wheel disable
		sense	disable	disable		key only	disable
v-flags	v-trig #2 sense	velocity trigger #2	velocity trigger #2 level		velocity trigger #1 level		evel





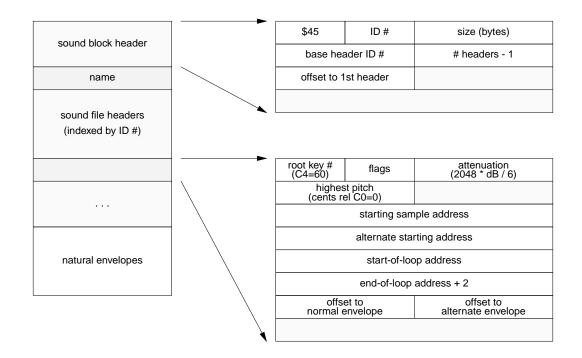
1000 Series LFO Tables

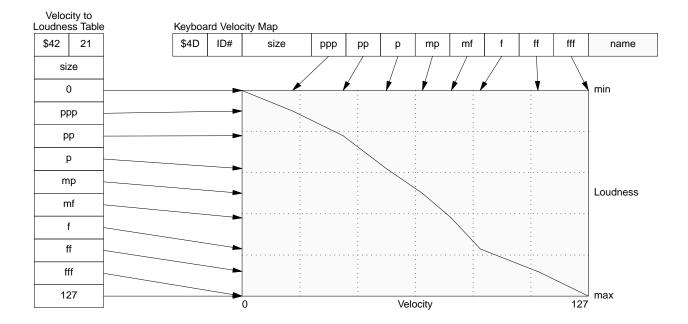




1000 Series Keymap Structure

1000 Series Sound Block Structure





1000 Series Velocity Mapping